

Matteo Tesori

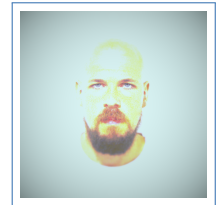
Curriculum vitae

via Trieste 32a
50065 Pontassieve (FI)
Italy

☎ +39 328 23 88 480

✉ matteo.tesori@unifi.it

Birth Date: 11/01/1991



Education

2005–2010 **High School Diploma**, *IISS Ernesto Balducci*, Pontassieve,
Final vote - 86/100

Specialized in informatics. Main topics:

- Assembly
- C
- C++
- Microsoft Access
- HTML
- Analog and digital electronics

2010–2017 **Bachelor's degree in Electronics and Telecommunications Engineering**, *University of Florence*, Florence,
Final vote - 104/110 (*Average vote*: 26.4/30)

Specialized in automation. Main topics:

Engineering

- Automation and control systems
- Signal processing
- Industrial robotics
- Linear circuits theory
- Analog and digital electronics
- Informatics (Assembly, BNF, C)

Mathematics

- Single variable, multivariable and vectorial calculus
- Complex analysis
- Linear algebra
- Operation research
- Numerical analysis
- Probability theory and inferential statistics

Physics

- Classical and Lagrangian Mechanics
- Electromagnetic fields

- 2017–2021 **Master's degree in Electrical and Automation Engineering**,
University of Florence, Florence, *Final vote* - 110/110 Summa
Cum Laude (Average vote: 29.7/30)
Specialized in automation. Main topics:
- Automation Engineering**
 - Adaptive, predictive and distributed control
 - Robust and non-linear control
 - Estimation and dynamic system identification
 - Mobile robotics
 - Industrial automation
 - Mathematics**
 - Real analysis
 - Non-linear dynamic systems
 - Optimization methods
 - Machine Learning
 - Electrical Engineering**
 - Mechatronics
 - Electric machines and power converters
 - Electric power systems

Bachelor's degree thesis

- title *Robust LQ control of an inverted pendulum*
- supervisors Professor Luigi Chisci
- description The main objective of the work was to design, via the theory of Linear Quadratic (LQ) regulator, and simulate, in Simulink, a control system for swinging up and stabilize an inverted pendulum based over an oscillating plan.

Master's degree thesis

- title *Multiple extended object tracking*
- supervisors Professor Luigi Chisci, Professor Giorgio Battistelli, Professor Lin Gao (University of Electronic Science and Technology of China, Chengdu)
- description The main objective of the work was to devise a new Probability Hypothesis Density (PHD) filter able to track simultaneously the position and the shape of multiple extended objects. The main contribution of the thesis consists in the definition of a new prediction model, called Lambda:Omicron motion model, that generalizes the well-known unicycle model.

Postgraduate education

2021–2024 **PhD course in Information Engineering (37th cycle)**, *Dipartimento di Ingegneria dell'Informazione (DINFO)*, University of Florence, Florence, student with regular scholarship (Final rank: 2nd over 50 attendees).

PhD program: estimation algorithms for autonomous driving. The main objective is to deliver new and innovative distributed filters for autonomous driving applications, starting from Random Finite Set (RFS) and Machine Learning solutions.

Awards

competition SSE CHALLENGE - ENGINEERING FOR INDUSTRY 4.0
year 2020
result 1st classified (1500 € prize)
project title Model predictive control of a differential drive autonomous vehicle.
project description The main objective of the work was to realize a simple autonomous vehicle capable to follow the path of an arbitrary road by measuring, via two ultrasonic sensors, the distance from the left and right borders of the road.

Computer skills

Basic HTML, Microsoft Access
Intermediate C++, C, Python, LabVIEW, Microsoft Office, Inkscape
Advanced \LaTeX , MATLAB, Ableton Live, Vegas Pro

Languages

Italian Mothertongue
English Intermediate (B1)